Vietnam Journal of Mathematics 40:1(2012) 57-78

# g-Navier-Stokes Equations with Infinite Delays

Cung The Anh1 and Dao Trong Quyet2

<sup>1</sup>Department of Mathematics. Hanoi National University of Education, 136 Xuan Thuy. Cau Giay, Hanoi, Vietnam

<sup>2</sup>Faculty of Information Technology, Le Quy Don Technical University, 100 Hoang Quoc Viet. Cau Giay, Hanoi, Vietnam

> Received July 13, 2011 Revised October 24, 2011

Abstract. We study the first initial boundary value problem for the two-dimensional non-autonomous g-Navier-Stokes equations containing infinite delay terms in an arbitrary (bounded or unbounded) domain satisfying the Poincaré inequality. The existence and uniqueness of a weak solution to the problem is proved by using the Galerkin method. Moreover, we also analyze the stationary problem and, under suitable additional conditions, we obtain global exponential decay of the solution of the evolutionary problem to the stationary solution.

2000 Mathematics Subject Classification. 35B41, 35Q30, 37L30, 35D05.

Key words. g-Navier-Stokes equations, infinite delay, weak solution, the Galerkin method, stationary solution, global stability.

## 1. Introduction

Let  $\Omega$  be a (bounded or unbounded) domain in  $\mathbb{R}^3$  with boundary  $\Gamma$ . In this paper we study the existence and long-time behavior of solutions to the following two-dimensional non-autonomous g-Navier-Stokes equations with infinite delays:

$$\begin{cases} \frac{\partial u}{\partial t} - \nu \Delta u + (u \cdot \nabla)u + \nabla p &= f(t) + F(t, u_t) \text{ in } (\tau, T) \times \Omega, \\ \nabla \cdot (gu) &= 0 \text{ in } (\tau, T) \times \Omega, \\ u &= 0 \text{ on } (\tau, T) \times \Gamma, \\ u(\tau + s, \tau) &= \phi(s, x), \ s \in (-\infty, 0], x \in \Omega, \end{cases}$$
(1)

where  $u = u(x,t) = (y_1, y_2)$  is the unknown velocity vector, p = p(x, t) is the unknown pressure,  $\nu > 0$  is the kinematic viscosity coefficient.

The g-Navier-Stokes equations is a variation of the standard Navier-Stokes equations. More precisely, when  $g \equiv \text{const}$  we get the usual Navier-Stokes equations. The 2D g-Navier-Stokes equations arise in a natural way when we study the standard 3D problem in thin domains. We refer the reader to [14] for a derivation of the 2D g-Navier-Stokes equations from the 3D Navier-Stokes equations and a relationship between them. As mentioned in [10], good properties of the 2D g-Navier-Stokes equations on the thin three-dimensional domain  $\Omega_g = \Omega \times (0,g)$ . Therefore, in the last few years, the existence and asymptotic behavior of solutions to g-Navier-Stokes equations to g-Navier-Stokes equations to g-Navier-Stokes equations (see ), (1, 2, N, 9, 10, 14).

However, there are situations in which the model is better described if some terms containing delays appear in the equations These delays may appear, for instance, when one wants to control the system (in a certain sense) by applying a force which takes into account not only the present state. but the complete history of the solutions. Therefore, in this paper we are interested in the case in which terms containing infinite delays appear. It is noticed that equations of Navier-Stokes type with delays in bounded domains has been studied in [3, 4, 5, 6] for the case of finite delays and very recently in [11, 12] for the case of infinite delays and very necessarily bounded to prove the existence and global stability of solutions of 2D g-Navier-Stokes equations in an infinite delay case and domains that are not necessarily bounded but satisfy the Poincaré inequality. The obtained results, in particular, extend and improve some recent ones for Navier-Stokes equations with infinite delays [1].

It is known that there are numerous technical difficulties in dealing with partial differential equations with infinite delays in unbounded domains due to the unboundedness of the delay involved, and because the Sobolev embeddings are no longer compact. These introduce a major obstacle for proving the existence of solutions. To overcome these difficulties, in this paper we try to combine the techniques used for Navier-Stokes equations in unbounded domains (see e.g. [15, 6]) and the techniques used in [11] in dealing with the infinite delays.

Let X be a Banach space. Given a function  $u : (-\infty, T) \to X$ , for each t < T we denote by u, the function defined on  $(-\infty, 0]$  by the relation  $u_t(s) = u(t+s), s \in (-\infty, 0]$ .

One possibility to deal with infinite delays, and which we will use here, is to consider, for any  $\gamma > 0$ , the space

$$C_{\gamma}(H_g) = \{\varphi \in C((-\infty, 0]; H_g) : \exists \lim_{s \to -\infty} e^{\gamma s} \varphi(s) \in H_g\},\$$

which is a Banach space with the norm

$$||\varphi||_{\gamma} := \sup_{s \in (-\infty,0]} e^{\gamma s} |\varphi(s)|.$$

Here the space  $H_g$  is defined in Section 2 below and  $|\cdot|$  denotes the norm in  $H_g$ . In order to study problem (1), we make the following assumptions:

(H1) The domain Ω can be an arbitrary (bounded or unbounded) domain in ℝ<sup>2</sup> without any regularity assumption on its boundary Γ, provided that the Poincaré inequality holds on Ω: There exists λ<sub>1</sub> > 0 such that

$$\int_{\Omega} \phi^2 g dx \leq \frac{1}{\lambda_1} \int_{\Omega} |\nabla \phi|^2 g dx \quad \forall \phi \in H^1_0(\Omega);$$

(H2) g ∈ W<sup>1,∞</sup>(Ω) such that

$$0 < m_0 \le g(x) \le M_0$$
 for all  $x = (x_1, x_2) \in \Omega$ , and  $|\nabla g|_{\infty} < m_0 \lambda_1^{1/2}$ ;

(H3)  $f \in L^2(\tau, T; V'_g)$ , where  $V'_g$  is the dual of the space  $V_g$  defined in Section 2; (H4)  $F(t, u_t) : (\tau, T) \times C_2(H_g) \to L^2(\Omega, g)$  such that

- (i)  $\forall \xi \in C_{\gamma}(H_{o})$ , the mapping  $(\tau, T) \ni t \mapsto F(t, \xi)$  is measurable,
- (ii) F(t, 0) = 0 for all t ∈ (τ, T),
- (iii) there exists a constant  $L_F > 0$  such that  $\forall t \in (\tau, T)$  and  $\xi, \eta \in C_{\gamma}(H_g)$ :

$$|F(t, \xi) - F(t, \eta)| \le L_F ||\xi - \eta||_{\gamma}$$
.

Here the space  $L^{2}(\Omega, g)$  is defined in Section 2 below.

We now give an example of the delay term  $F(t, u_t)$ . Let  $F : (\tau, T) \times C_{\gamma}(H_g) \to L^2(\Omega, g)$  be defined as follows

$$F(t,\xi) = \int_{-\infty}^{0} G(t,s,\xi(s)) ds \quad \forall t \in (\tau,T), \xi \in C_{\gamma}(H_g),$$

where the function  $G : (\tau, T) \times (-\infty, 0) \times \mathbb{R}^2 \to \mathbb{R}^2$  satisfies the following assumptions:

- G(t, s, 0) = 0 for all (t, s) ∈ (τ, T) × (−∞, 0);
- There exists a function κ : (-∞, 0) → (0,∞) such that

$$\begin{aligned} \|G(t,s,u) - G(t,s,v)\|_{\mathbb{R}^2} &\leq \kappa(s) \|u - v\|_{\mathbb{R}^2} \\ &\forall u, v \in \mathbb{R}^2, \forall (t,s) \in (\tau, T^*) \times (-\infty, 0), \end{aligned}$$

and the function  $\kappa$  satisfies that  $\kappa(\cdot)e^{-(\gamma+\varepsilon)\cdot} \in L^2(-\infty,0)$  for some  $\varepsilon > 0$ .

Then the function F satisfies (II4). Indeed, (H4-i) and (H4-ii) are obviously satisfied, for (H4-iii) we have

$$\begin{split} |F(l,\xi) - F(l,\eta)|^2 \\ &\int_{l_l} \left( \int_{-\infty}^0 \kappa(s) \|\xi(s)(x) - \eta(s)(x)\|_{\mathbb{R}^2} ds \right)^2 dx \\ &\leq \int_{l_l} \left( \int_{-\infty}^0 \kappa^2(s) e^{-2(\gamma+\varepsilon)s} ds \right) \left( \int_{-\infty}^0 e^{2(\gamma+\varepsilon)s} \|\xi(s)(x) - \eta(s)(x)\|_{\mathbb{R}^2}^2 ds \right) dx \\ &= \|\kappa(\cdot)e^{-(\gamma+\varepsilon)}\|_{L^2(-\infty,0)}^2 \int_{-\infty}^0 \int_{l_l} e^{2(\gamma+\varepsilon)s} \|\xi(s)(x) - \eta(s)(x)\|_{\mathbb{R}^2}^2 dx ds \\ &\leq \|\kappa(\cdot)e^{-(\gamma+\varepsilon)}\|_{L^2(-\infty,0)}^2 \left[ \sup_{s\in\{-\infty,0\}} e^{2\gamma s} \int_{l_l} \|\xi(s)(x) - \eta(s)(x)\|_{\mathbb{R}^2}^2 dx \right] \int_{-\infty}^0 e^{2\varepsilon s} ds \\ &= \|\kappa(\cdot)e^{-(\gamma+\varepsilon)}\|_{L^2(-\infty,0)}^2 \|\xi - \eta\|_{\gamma}^2 \frac{1}{2\varepsilon} \end{split}$$

The rest of the paper is organized as follows. In the next section, we recall some auxiliary results on function spaces and inequalities for the nonlinear terms, which are related to the *g*-Navier-Stokes equations. In Section 3, we prove the existence of a weak solution to problem (1) by using the Galerkin method. The existence, uniqueness and global stability of a stationary solution are studied in the last section under some additional conditions.

#### 2. Preliminary results

Let  $L^2(\varOmega,g)=(L^2(\varOmega))^2$  and  $H^1_0(\varOmega,g)=(H^1_0(\varOmega))^2$  be endowed, respectively, with the inner products

$$(u, v)_g = \int_{\Omega} u \cdot vgdx, \ u, v \in L^2(\Omega, g),$$

and

$$((u,v))_g = \int_{\Omega} \sum_{j=1}^{2} \nabla u_j \cdot \nabla v_j g dx, \ u = (u_1, u_2), v = (v_1, v_2) \in H^1_0(\Omega, g),$$

and norms  $|u|^2 = (u, u)_g$ ,  $||u||^2 = ((u, u))_g$ . Thanks to assumption (H2), the norms  $|\cdot|$  and || are equivalent to the usual ones in  $(L^2(\Omega))^2$  and in  $(H_0^1(\Omega))^2$ .

Let

$$V = \{u \in (C_0^{\infty}(\Omega))^2 : \nabla \cdot (gu) = 0\}.$$

Denote by  $H_g$  the closure of  $\mathcal{V}$  in  $L^2(\Omega, g)$ , and by  $V_g$  the closure of  $\mathcal{V}$  in  $H_0^1(\Omega, g)$ . It follows that  $V_g \subset H_g \equiv H'_g \subset V'_g$ , where the injections are dense and continuous. We will use  $\|\cdot\|$ . for the norm in  $V'_g$ , and  $\langle \cdot \cdot \rangle$  for duality priving between  $V_g$  and  $V'_g$ .

We now define the trilinear form b by

$$b(u, v, w) = \sum_{i,j=1}^{2} \int_{\Omega} u_i \frac{\partial v_j}{\partial r_i} w_j g dv.$$

whenever the integrals make sense. It is easy to check that if  $u, v, w \in V_q$ , then

$$b(u, v, w) = -b(u, w, v).$$

Hence

$$b(u, v, v) = 0$$
 and  $b(u, u, u - v) - b(v, v, u - v) = b(u - v, v, u - v) \forall u, v \in V_g$ .

Set  $A: V_g \to V'_g$  by  $(Au, v) = ((u, r))_q$   $B: V_g \times V_g \to V'_g$  by (B(u, v), w) = b(u, v, w). Denote  $D(A) = \{u \in V_g - Au \in H_g\}$ , then  $D(A) = H^2(\Omega, g) \cap V_g$  and  $Au = -P_g \Delta u \ \forall u \in D(A)$ , where  $P_g$  is the ortho-projector from  $L^2(\Omega, g)$  onto  $H_g$ 

Using the Hölder inequality, the Ladyzhenskaya inequality (when n = 2)

$$|u|_{L^{1}} \le c|u|^{1/2} |\nabla u|^{1/2} \quad \forall u \in H_{0}^{1}(\Omega),$$

and the interpolation inequalities, as in [15] one can prove the following

## Lemma 2.1. If n = 2, then

$$|b(u, v, w)| \leq \begin{cases} c_1 |u|^{1/2} ||u||^{1/2} ||v|| ||w|^{1/2} ||w||^{1/2} & \forall u, v, w \in V_g. \\ c_2 |u|^{1/2} ||u||^{1/2} ||v|| ||Aw|^{1/2} ||w||^{1/2} & \forall u \in V_g, v \in D(A), w \in H_g. \\ c_3 |u|^{1/2} ||Au|^{1/2} ||v|| ||w| & \forall u \in D(A), v \in V_g, w \in H_g. \\ c_4 ||u|| ||v|| ||w|^{1/2} ||Aw|^{1/2} & \forall u \in H_g, v \in V_g, w \in D(A), \end{cases}$$

where  $c_i, i = 1, ..., 4$ , are appropriate constants.

Lemma 2.2. [2] Let  $u \in L^2(\tau, T; V_g)$ , then the function Bu defined by

$$(Bu(t), v)_g = b(u(t), u(t), v) \quad \forall v \in V_g, a.e. t \in [\tau, T],$$

belongs to  $L^2(\tau, T; V'_q)$ .

Lemma 2.3. [2] Let  $u \in L^2(\tau, T; V_q)$ , then the function Cu defined by

$$(Cu(t), v)_g = ((\frac{\nabla g}{g} \cdot \nabla)u, v)_g = b(\frac{\nabla g}{g}, u, v) \quad \forall v \in V_g,$$

belongs to  $L^2(\tau, T; H_g)$ , and hence also belongs to  $L^2(\tau, T; V'_g)$ . Moreover,

$$|Cu(t)| \le \frac{|\nabla g|_{\infty}}{m_0} \cdot |u(t)|$$
 for a.e.  $t \in (\tau, T)$ .

and

$$\|Cu(t)\|_{*} \leq \frac{|\nabla g|_{\infty}}{m_{0}\lambda_{1}^{1/2}} \cdot \|u(t)\|$$
 for a.e.  $t \in (\tau, T)$ 

Since

$$-\frac{1}{g}(\nabla \cdot g\nabla)u = -\Delta u - (\frac{\nabla g}{g} \cdot \nabla)u.$$

we have

$$(-\Delta u, v)_g = ((u, v))_g + (\{\frac{\nabla g}{g} \cdot \nabla)u, v)_g = (Au, v)_g + (Cu, v)_g \quad \forall u, v \in V_g$$

Denote by  $\mathcal{V}(\mathcal{O})$  the same space as  $\mathcal{V}$  but with an open set  $\mathcal{O}$  instead of  $\Omega$ , and analogously define  $V_g(\mathcal{O})$  the closure of  $\mathcal{V}(\mathcal{O})$  in  $H^1_0(\mathcal{O}, g)$ ,  $H_g(\mathcal{O})$  the closure of  $\mathcal{V}(\mathcal{O})$  in  $L^2(\mathcal{O}, g)$ , and  $D(\mathcal{A}(\mathcal{O})) = H^2(\mathcal{O}, g) \cap V_g(\mathcal{O})$ .

#### 3. Existence and uniqueness of weak solutions

**Definition 3.1.** A weak solution on the interval  $(\tau, T)$  of problem (1) is a function  $u \in C((-\infty, T]; H_g) \cap L^2(\tau, T; V_g)$  with  $u_\tau = \phi$ , and such that for all  $v \in V_g$ ,

$$\frac{d}{dt}(u(t), v)_g + \nu((u(t), v))_g + b(u(t), u(t), v) + \nu(Cu(t), v)_g = \langle f(t), v \rangle + (F(t, u_t), v)_g, (3) \rangle$$

in the sense of  $D'(\tau, T)$ .

It is noticed that if u is a weak solution of (1), then u satisfies the following energy equality

$$\begin{split} & \|u(t)\|^2 + 2\nu \int_s^t \||u(r)\|^2 dr + 2\nu \int_s b(\frac{\nabla g}{g}, u(r), u(r)) dr \\ & = \|u(s)\|^2 + 2 \int_s^t \Big[ (f(r), u(r)) + (F(r, u_r), u(r))_g \Big] dr. \end{split}$$

**Theorem 3.2.** Suppose that  $\phi \in C_{\gamma}(H_g)$  is given and that  $2\gamma > \nu\lambda_1\gamma_0$ , where  $\gamma_0 = 1 - \frac{|\nabla g|_{\infty}}{m_0\lambda_1^{1/2}} > 0$ . Then, there exists a unique weak solution u of problem (1) on the interval  $(\tau, T)$ .

*Proof.* (i) Uniqueness. Let u, v be two weak solutions of problem (1) with the same initial condition and set w = u - v. Then, using the energy equality, we obtain

$$\begin{split} |w(t)|^2 &+ 2\nu \int_{\tau}^{t} ||w(s)||^2 ds + 2\nu \int_{\tau}^{t} b(\frac{\nabla g}{g}, w(s), w(s)) ds \\ &= -2 \int_{\tau}^{t} b(w(s), v(s), w(s)) ds + 2 \int_{\tau}^{t} (F(s, u_s) - F(s, v_s), w(s))_g ds. \end{split}$$

By Lemmas 2.1 and 2.3, we have

$$\begin{split} \left| 2 \int_{\tau}^{t} b(w(s), v(s), w(s)) ds \right| &\leq 2c_1 \int_{\tau} \|w(s)\| \|w(s)\| \|v(s)\| ds \\ &\leq \nu \int_{\tau}^{t} \|w(s)\|^2 ds + \frac{c_1^2}{\nu} \int_{\tau} \|v(s)\|^2 |w(s)|^2 ds \end{split}$$

and

$$\begin{aligned} \left| 2\nu \int_{\tau}^{\tau} b(\frac{\nabla g}{g}, w(s), w(s)) ds \right| &\leq 2\nu \frac{|\nabla g|_{\infty}}{m_0 \lambda_1^{1/2}} \int_{\tau}^{t} ||w(s)|||w(s)|| ds \\ &\leq \nu \int_{\tau}^{t} ||w(s)||^2 ds + \frac{\nu |\nabla g|_{\infty}^2}{m_0^2 \lambda_1} \int_{\tau} |w(s)|^2 ds. \end{aligned}$$

Because of (H4-iii). we have

$$\begin{split} \left| 2 \int_{\tau}^{t} (F(s, u_s) - F(s, v_s), w(s)) ds \right| &\leq 2 \int_{\tau}^{t} |F(s, u_s) - F(s, v_s)| |w(s)| ds \\ &\leq 2 L_F \int_{\tau} ||w_s||_{\gamma} |w(s)| ds. \end{split}$$

Since  $w(s) = 0 \forall s \leq \tau$ , we have

$$\begin{split} \|w_s\|_{\gamma} &= \sup_{\theta \leq 0} e^{\gamma \theta} |w(s + \theta)| \\ &\leq \sup_{\theta \in [\tau - s, 0]} e^{\gamma \theta} |w(s + \theta)| \text{ for } \tau \leq s \leq T. \end{split}$$

Therefore, one has

$$|w(t)|^2 \leq \frac{c_1^2}{\nu} \int_{\tau} \|v(s)\|^2 |w(s)|^2 ds + \left(2L_F + \frac{\nu |\nabla g|_\infty^2}{m_0^2 \lambda_1}\right) \int_{\tau}^t \sup_{r \in [\tau,s]} |w(\tau)|^2 ds.$$

Hence we deduce that

$$\sup_{r \in [\tau,t]} |w(r)|^2 \leq \int_{\tau}^{\tau} \left( 2L_F + \frac{\nu |\nabla g|_{\infty}^2}{m_0^2 \lambda_1} + \frac{c_1^2}{\nu} \|v(s)\|^2 \right) \sup_{r \in [\tau,s]} |w(r)|^2 ds,$$

whence the Gronwall inequality completes the proof of uniqueness.

(ii) Existence. We split the proof of the existence into several steps.

Step 1. A Galerkin scheme. Since  $V_g$  is separable and V is dense in  $V_g$ , there exists

a sequence of linearly independent elements  $\{v_1, v_2, ...\} \subset \mathcal{V}$  which is total in  $V_g$ . Denote  $V_m = \operatorname{span}\{v_1, ..., v_m\}$  and consider the projector  $P_m u = \sum_{j=1}^m (u, v_j)v_j$ . Define also

$$u^{m}(t) = \sum_{j=1}^{m} \alpha_{m,j}(t)v_{j}$$

where the coefficients on, are required to satisfy the following system

$$\frac{d}{dt} (u^{m}(t), v_{j})_{g} + \nu \langle Au^{m}(t), v_{j} \rangle + \nu (Cu^{m}(t), v_{j})_{g} + b(u^{m}(t), u^{m}(t), v_{j})$$

$$= \langle f(t), v_{j} \rangle + (F(t, u^{m}_{t}), v_{j})_{g} \quad \forall j = 1, ..., m,$$
(4)

and the initial condition  $u^{m}(\tau + s) = P_{m}\phi(s)$  for  $s \in (-\infty, 0]$ .

The above system of ordinary functional differential equations with infinite delay in the unknown  $(\alpha_{m,1}(t), ..., \alpha_{m,m}(t))$  fulfills the conditions for existence and uniqueness of local solutions (see [7, Theorem 1.1, p. 36]), so the approximate solutions  $u_m$  exist.

Step 2. A priori estimates. Multiplying (4) by  $\alpha_{m,j}(t)$  and summing in j, we obtain

$$\frac{d}{dt}(u^{m}(t), u^{m}(t))_{g} + \nu(Au^{m}(t), u^{m}(t)) + \nu(Cu^{m}(t), u^{m}(t))_{g} + b(u^{m}(t), u^{m}(t), u^{m}(t)) = (f(t), u^{m}(t)) + (F(t, u^{m}_{t}), u^{m}(t))_{g}$$
(5)

Because  $b(u^{m}(t), u^{m}(t), u^{m}(t)) = 0$  and  $(Cu^{m}(t), u^{m}(t))_{g} = b(\frac{\nabla g}{g}, u^{m}(t), u^{m}(t)),$ from (5) we have

$$\frac{d}{dt}(u^m(t), u^m(t))_g + \nu \langle Au^{n_1}(t), u^{n_1}(t) \rangle + \nu b(\frac{\nabla g}{g}, u^{n_1}(t), u^m(t))$$

$$(f(t), u^m(t)) + (F(t, u^m_t), u^m(t))_g$$

and therefore,

$$\frac{d}{dt}|u^{m}(t)|^{2} + 2\nu ||u^{m}(t)||^{2} = 2(f(t), u^{m}(t)) + 2(F(t, u^{m}_{t}), u^{m}(t))_{g} - 2\nu b(\frac{\nabla g}{g}, u^{m}(t), u^{m}(t))$$
(6)

Using the Cauchy inequality and Lemma 2.3, we get

$$\frac{d}{dt} \|u^{m}(t)\|^{2} + 2\nu \|u^{m}(t)\|^{2} \le 2\epsilon\nu \|u^{m}(t)\|^{2} + \frac{\|f(t)\|^{2}}{2\epsilon\nu} + 2L_{F} \|u^{m}_{t}\|^{2}_{\gamma} + 2\nu \frac{\|\nabla g\|_{\infty}}{m_{0}\lambda_{1}^{1/2}} \|u^{m}(t)\|^{2}$$

and hence

$$\frac{d}{dt}|u^{m}(t)|^{2} + 2\nu(\gamma_{0} - \epsilon)||u^{m}(t)||^{2} \leq 2\left(\frac{\|f(t)\|_{*}^{2}}{4\epsilon\nu} + L_{F}||u^{m}_{\ell}||_{\gamma}^{2}\right).$$
(7)

where  $\gamma_0 = 1 - \frac{|\nabla e|_{p_0}}{m_0 \lambda_1^{1/2}} > 0$  and  $\epsilon > 0$  is chosen such that  $\gamma_0 - \epsilon > 0$ . Noting that  $||u^m(t)||^2 \ge \lambda_1 |u^m(t)|^2$ , we also have

$$\frac{d}{dt} |u^{m}(t)|^{2} + \nu \lambda_{1} (\gamma_{0} - \epsilon) |u^{m}(t)|^{2} + \nu (\gamma_{0} - \epsilon) ||u^{m}(t)||^{2} \leq 2 \Big( \frac{||f(t)||_{*}^{2}}{4\epsilon\nu} + \iota_{F} ||u^{m}_{i}||_{\gamma}^{2} \Big)$$

Hence

$$|u^{m}(t)|^{2} + \nu(\gamma_{0} - \epsilon) \int_{\tau}^{t} e^{-\nu\lambda_{1}(\gamma_{0} - \epsilon)(t-\gamma)} ||u^{m}(s)||^{2} ds$$

$$\leq e^{-\nu\lambda_{1}(\gamma_{0} - \epsilon)(t-\gamma)} ||u^{m}(\tau)|^{2} + 2 \int_{\tau}^{t} e^{-\nu\lambda_{1}(\gamma_{0} - \epsilon)(t-\gamma)} \left[ \frac{||f(s)||_{s}^{2}}{4\epsilon\nu} + L_{F} ||u^{m}_{s}||_{\gamma}^{2} \right] ds.$$
(8)

Furthermore,

$$\begin{split} \|u_t^m\|_{\gamma}^2 &\leq \max\left\{\sup_{\theta\in\{-\infty,\tau-t\}} e^{2\gamma\theta} |\phi(\theta+t-\tau)|^2 \sup_{\theta\in[\tau-t,0]} \left[e^{2\gamma\theta-\nu\lambda_1(\gamma_0-\iota)(t-\tau+\theta)} |u(\tau)|^2 \right. \right. \\ &+ 2e^{2\gamma\theta} \int_{\tau}^{t+\theta} e^{-\nu\lambda_1(\gamma_0-\iota)(t+\theta-\theta)} \left(\frac{\|f(s)\|^2}{4\epsilon\nu} + L_F \|u_s^m\|_{\gamma}^2 ds\right]\right\}. \end{split}$$

On one hand,

$$\sup_{\theta \in (-\infty, \tau - t]} e^{\gamma \theta} |\phi(\theta + t - \tau)| = \sup_{\theta \le 0} e^{\gamma(\theta - \{t - \tau\})} |\phi(\theta)| = e^{-\gamma(t - \tau)} ||\phi||_{\gamma}.$$

On the other hand, as we are assuming that  $2\gamma > \nu \lambda_1 \gamma_0$ ,

$$\sup_{\theta \in [\tau-\tau,0]} e^{2\gamma \theta - \nu \lambda_1 (\gamma_0 - \epsilon)(t-\tau+\theta)} |u(\tau)|^2 \le e^{-\nu \lambda_1 (\gamma_0 - \epsilon)(t-\tau)} |u(\tau)|^2$$

and

$$\sup_{\substack{\theta \in [\tau-t,0]}} e^{2\gamma\theta} \int_{\tau}^{t+\theta} e^{-\nu\lambda_1(\gamma_0-\epsilon)(t+\theta-\epsilon)} \left(\frac{\|f(s)\|_{\tau}^2}{4\epsilon\nu} + L_F \|u_s^m\|_{\gamma}^2\right) ds$$

$$\leq \int_{\tau}^{t+\theta} e^{-\nu\lambda_1(\gamma_0-\epsilon)(t-s)} \left(\frac{\|f(s)\|_{\tau}^2}{4\epsilon\nu} + L_F \|u_s^m\|_{\gamma}^2\right) ds.$$

Combining these inequalites we deduce that

$$\|u_t^m\|_{\gamma}^2 \le e^{-\nu\lambda_1(\gamma_0 - \epsilon)(t - \tau)} \|\phi\|_{\gamma}^2 + 2\int_{\tau}^t e^{-\nu\lambda_1(\gamma_0 - \epsilon)(t - s)} \Big(\frac{\|f(s)\|_{\star}^2}{4\epsilon\nu} + L_F \|u_s^m\|_{\gamma}^2\Big) ds.$$

By the Gronwall lemma we have

$$\|u_t^m\|_{\gamma}^2 \leq e^{-[\nu\lambda_1(\gamma_0-\epsilon)-2L_F](t-\tau)}\|\phi\|_{\gamma}^2 + \frac{1}{2\epsilon\nu}\int_{\tau}^t e^{-[\nu\lambda_1(\gamma_0-\epsilon)-2L_F](t-s)}\|f(s)\|_{*}^2 ds.$$

Then we obtain the following estimates: for any R > 0 such that  $\|\phi\|_{\gamma} \leq R$ , there exists a constant  $C_1$  depending on  $\lambda_1, \nu, L_F, \tau, f, R, \tau$ , such that

$$||u_t^m||_{\gamma}^2 \le C_1 \quad \forall t \in [\tau, T], m \ge 1.$$
 (9)

In particular, this implies that

$$\{u^m\}$$
 is bounded in  $L^{\infty}(\tau, T; H_q)$ . (10)

Integrating (7) from  $\tau$  to T, we have

$$\begin{split} |u^{m}(T)|^{2} + 2\nu(\gamma_{0} - \epsilon) \int_{\tau}^{T} ||u^{m}(s)||^{2} ds &\leq |u(\tau)|^{2} + 2 \int_{\tau}^{T} \left[ \frac{||f(s)||^{2}}{4\epsilon\nu} + L_{F} ||u^{m}_{s}||^{2}_{\gamma} \right] ds \\ &\leq R^{2} + 2 \int_{\tau}^{T} \left[ \frac{||f(s)||^{2}}{|\epsilon\nu} + L_{F}C_{1} \right] ds, \end{split}$$

thus, there exists a constant  $C_2$  depending on  $R, C_1$  such that

$$||u^m||_{L^2(\tau,T,V_p)}^2 \le C_2 \quad \forall m \ge 1.$$
 (11)

This implies that  $\{u^m\}$  is bounded in  $L^2(\tau, T, V_g)$ .

Now, observe that (4) is equivalent to

$$\frac{du^{m}}{dt} = -\nu A u^{m} - \nu C u^{m} - P_{m} B(u^{m}, u^{m}) + P_{m} f(t) + P_{m} F(t, u_{t}^{m}).$$
(12)

Hence, we have

$$\{(u^{m})'\}$$
 is bounded in  $L^{2}(\tau, T, V_{\eta})$  (13)

So, there exist  $u \in L^{\infty}(\tau, T; H_g) \cap L^2(\tau, T; V_q)$  with  $u' \in L^2(\tau, T; V_q')$  and a subsequence of  $\{u^m\}$ , relabelled the same, such that

 $\{u^m\}$  converges weakly-star to u in  $L^{\infty}(\tau, T, H_g)$ ,  $\{u^m\}$  converges weakly to u in  $L^2(\tau, T; V_g)$ .  $\{(u^m)'\}$  converges weakly to u' in  $L^2(\tau, T; V_g)$ .

If  $\Omega$  is bounded, then the Aubin-Luons lemma in [13, Chapter 1] allows us to obtain a compactness result: a subsequence  $u^m$  converges to u in  $L^2(\tau, T: H_0)$ . If  $\Omega$  is unbounded, we will have a similar result but not in a straightforward way, nor on the whole domain  $\Omega$ . Actually, what holds in this case is the following: For any bounded open set  $\mathcal{O} \subset \Omega$  there exists a subsequence (depending on  $\mathcal{O}$ which we relabel) satisfying

$$u^m |_{\mathcal{O}} \rightarrow u|_{\mathcal{O}} \text{ in } L^2(\tau, T; (L^2(\mathcal{O}, g)).$$
 (14)

For the sake of clarity, we postpone the proof to Lemma 3.4 below. Then we can pass to the limit in the term  $b(u^m, u^m, \cdot)$  thanks to the following lemma whose proof is exactly the proof of Lemma 3.2 in [15, Chapter III]. Lemma 3.3. If  $u_m$  converges to u in  $L^2(\tau, T; V_\eta(\mathbb{O}))$  weakly and in  $L^2(\tau, T; H_g(\mathcal{O}))$  strongly, where O is an open bounded set, then for any vector function w with components belonging to  $\mathbb{C}^4(\overline{O})$ , we have

$$\int_{\tau}^{T} b(u_m(t), u_m(t), w(t)) dt \to \int_{\tau}^{T} b(u(t), u(t), w(t)) dt$$

However, the estimates obtained above are not enough to pass to the limit in the term  $F(t, u_t^m)$ .

Step 3. Convergence in  $C_{\gamma}(H_{\eta}(\mathbb{O}))$  and existence of a weak solution.

We will prove that

$$u_t^m \rightarrow u_t$$
 in  $C_{\gamma}(H_g(\mathcal{O})) \quad \forall t \in \{-\infty, T\}$ .

It is not difficult to check that this holds if we prove the following

$$P_m \phi \rightarrow \phi \text{ in } C_{\gamma}(H_g(\mathcal{O})).$$
 (15)

$$u^m \rightarrow u$$
 in  $C([\tau, T], H_g(O))$  (16)

Step 3.1. Approximation in  $C_{\gamma}(H_q(O))$  of the initial datum.

We now check the convergence claimed in (15). Indeed, if not, there would exist  $\epsilon > 0$  and a subsequence, that we relabel the same, such that

$$e^{\gamma \theta_m} |P_m \phi(\theta_m) - \phi(\theta_m)| > \epsilon.$$
 (17)

One can assume that  $\theta_m \to -\infty$  otherwise if  $\theta_m \to \theta$ , then  $P_m\phi(\theta_m) \to \phi(\theta)$ , since  $|P_m\phi(\theta_m) - \phi(\theta)| \leq |P_m\phi(\theta_m) - P_m\phi(\theta)| + |P_m\phi(\theta) - \phi(\theta)| \to 0$  as  $m \to +\infty$ . But with  $\theta_m \to -\infty$  as  $m \to +\infty$ , if we denote  $x = \lim_{\theta \to -\infty} e^{\gamma\theta}\phi(\theta)$ , we obtain that

$$e^{\gamma \theta_m} |P_m \phi(\theta_m) - \phi(\theta_m)| = |P_m(e^{\gamma \theta_m} \phi(\theta_m)) - e^{\gamma \theta_m} \phi(\theta_m)|$$
  
 $\leq |P_m(e^{\gamma \theta_m} \phi(\theta_m)) - P_m x| + |P_m x - x| + |x - e^{\gamma \theta_m} \phi(\theta_m)| \rightarrow 0.$ 

This is a contradiction with (17), so (15) holds.

Step 3.2. Convergence of  $u^m$  to u in  $C([\tau, T]; H_g(O))$ .

From the strong convergence of  $\{u^m\}$  to u in  $L^2(\tau, T; H_g(O))$ , we deduce that

$$u^{m}(t) \rightarrow u(t)$$
 in  $H_{g}(O)$  a.e.  $t \in (\tau, T)$ .

Since

$$u^m(t) - u^m(s) = \int_s^t (u^m)'(r) dr \text{ in } V_g'(\mathcal{O}) \quad \forall s, t \in [\tau, T],$$

from (13) we have that  $\{u^m\}$  is equi-continuous on  $[\tau, T]$  with values in  $V'_g(\mathcal{O})$ . By the compactness of the embeding  $H_g(\mathcal{O}) \subset V'_g(\mathcal{O})$ , from (10) and the equicontinuity in  $V'_a(\mathcal{O})$ , using the Arzela-Ascoli theorem we have

C. T. Anh, D. T. Quyet

$$u^m \rightarrow u$$
 in  $C([\tau, T]; V'_q(O)).$  (18)

Again from (10) we obtain that for any sequence  $\{t_m\} \subset [\tau, T]$  with  $t_m \to t$ ,

$$u^{m}(t_{m}) \rightarrow u(t)$$
 weakly in  $H_{q}(O)$ , (19)

where we have used (18) in order to identify which is the weak limit.

Now, we are ready to prove (16) by a constant router argument. If it would not be so, then taking into account that  $u \in C([\tau, T]; H_g(O))$ , there would exist e > 0, a value  $t_0 \in [\tau, T]$  and subsequences (relabelled the same)  $\{u^m\}$  and  $\{t_m\} \subset [\tau, T]$  with  $\min_{m \to +\infty} t_m = t_0$  such that

$$|u^{m}(t_{m}) - u(t_{0})| \ge \epsilon \quad \forall m.$$
 (20)

To prove that this is absurd, we will use an energy method. Observe that the following energy inequality holds for all  $u^m$ :

$$\frac{1}{2}|u^{m}(t)|^{2} + \nu(1 - \frac{|\nabla g|_{\infty}}{m_{0}\lambda_{1}^{1/2}})\int_{s}^{t}||u^{m}(r)||^{2}dr$$

$$\leq \int_{s}^{1}\langle f(r), u^{m}(r)\rangle dr + \frac{1}{2}|u^{m}(s)|^{2} + C_{3}(t-s) \quad \forall \ s, t \in [\tau, T],$$
(21)

where  $C_3 = \frac{D}{2\nu\lambda_1}$  and D corresponds to the upper bound

$$\int_{s}^{t} |F(r, u_{r}^{m})|^{2} dr \leq D(t-s) \quad \forall \ \tau \leq s < t \leq T$$

On the other hand, from (10), (H4-ii), (H4-iii), there exists  $\xi_F \in L^2(\tau, T; L^2(\mathcal{O}, g))$ such that  $\{F(t, u^m)\}$  converges weakly to  $\xi_F$  in  $L^2(\tau, T; L^2(\mathcal{O}, g))$ . Thus, we can pass to the limit in equation (12) and deduce that u is a solution of

$$\frac{d}{dt}(u(t), v)_g + \nu(\{u(t), v\})_g + \nu(Cu(t), v)_g + b(u(t), u(t), v) = \langle f(t), v \rangle + (\xi_F(t), v)_g.$$
(22)

Therefore, u satisfies the energy equality

$$\begin{split} & \|u(t)\|^2 + 2\nu \int_s^t \||u(\tau)\|^2 d\tau + 2\nu \int_s^t (Cu(r), u(\tau))_g d\tau \\ & = \|u(s)\|^2 + 2 \int_s^t \left( \langle f(r), u(\tau) \rangle + (\xi_F(r), u(\tau))_g \right) d\tau \quad \forall s, t \in [\tau, T], \end{split}$$

and for the weak limit  $\xi_F$  we have the estimate

$$\int_{s}^{t} |\xi_{F}|^{2} dr \leq \liminf_{m \to +\infty} \int_{s}^{t} |F(r, u_{r}^{m})|^{2} dr \leq D(t-s) \quad \forall r \leq s \leq t \leq T.$$

So, we have that u also satisfies inequality (21) with the same constant  $C_3$ . Now, consider two functions  $J_m, J : [\tau, T] \to \mathbb{R}$  defined by

$$\begin{split} J_m(t) &= \frac{1}{2} |u^m(t)|^2 - \int_{\tau}^{t} \langle f(r), u^m(r) \rangle dr - C_3 t \\ J(t) &= \frac{1}{2} |u(t)|^2 - \int_{\tau}^{t} \langle f(r), u(r) \rangle dr - C_3 t. \end{split}$$

It is clear that  $J_m$  and J are non-increasing and continuous functions. Moreover, by the convergence of  $u^m$  to u a.e. in time with value in  $H_g(\mathcal{O})$ , and weakly in  $L^2(r, T; H_g(\mathcal{O}))$ , it holds that

$$J_m(t) \rightarrow J(t)$$
 a.e.  $t \in [\tau, T]$ . (23)

Now we will prove that

$$u^m(t_m) \rightarrow u(t_0)$$
 in  $H_g(O)$ , (24)

which contradicts (20). First, recall from (19) that

$$u^{m}(t_{m}) \rightarrow u(t_{0})$$
 weakly in  $H_{g}(O)$ , (25)

so we have

$$|u(t_0)| \le \liminf_{m \to +\infty} |u^m(t_m)|$$

Therefore, if we show that

$$\limsup_{m \to +\infty} |u^{m}(t_{m})| \le |u(t_{0})|, \quad (26)$$

we will obtain that  $\lim_{m \to +\infty} |u^m(t_m)| = |u(t_0)|$ , which jointly with (25) imply (24).

Now, observe that the case  $t_0 = \tau$  follows directly from (21) with  $s = \tau$ and the definition of  $u^m(\tau) = P_m\phi(0)$ . So, we may assume that  $t_0 > \tau$ . This is important, since we will approach this value  $t_0$  from the left by a sequence  $\{t_k^*\}$ , i.e.  $\lim_{k \to +\infty} t_k^* > t_0$ . Since u(.) is continuous at  $t_0$ , there is  $k_\epsilon$  such that

$$|J(t'_k) - J(t_0)| < \frac{\epsilon}{2} \quad \forall \ k \ge k_\epsilon$$

On the other hand, taking  $m \ge m(k_c)$  such that  $t_m > t'_{k_s}$ , as  $J_m$  is non-increasing and for all  $t'_k$  the convergence (24) holds, one has

$$J_m(t_m) - J(t_0) \le |J_m(t'_{k_\ell}) - J(t'_{k_\ell})| + |J(t'_{k_\ell}) - J(t_0)|,$$

and obviously, taking  $m \leq m'(k_{\epsilon})$ , it is possible to obtain  $|J_m(t'_{k_{\epsilon}}) - J(t'_{k_{\epsilon}})| < \frac{\epsilon}{2}$ . It can also be deduced from Step 2 that

$$\int_{\tau}^{t_m} \langle f(r), u^m(r) \rangle d\tau \to \int_{\tau}^{t_0} \langle f(r), u(r) \rangle d\tau,$$

so we conclude that (26) holds. Thus, (24) and finally (16) are also true, as we

wanted to check. Hence, we have

$$F(\cdot, u^m) \rightarrow F(\cdot, u)$$
 in  $L^2(\tau, T; L^2(\mathcal{O}, g))$ . (27)

In what follows we will show that the convergence results above enable us to conclude that a is a solution of problem (1). Let  $\psi$  be a continuously differentiable function on [0, 7]. Mulpying (1) by  $\psi(t)$ , we have

$$\begin{split} &\int_{\tau}^{T} \left(\frac{du^{m}(t)}{dt}, u_{j}\psi(t)\right)_{g} dt + \nu \int_{\tau}^{\tau} \langle Au^{m}(t), u_{j}\psi(t) \rangle dt \\ &+ \nu \int_{\tau}^{T} (Cu^{m}(t), v_{j}\psi(t))_{g} dt + \int_{\tau}^{T} b(u^{m}(t), u^{m}(t), v_{j}\psi(t)) du \\ &\int_{\tau}^{t} \langle f(t), v_{j}\psi(t) \rangle dt + \int_{\tau}^{T} (F(t, u_{t}^{m}), v_{t}\psi(t))_{g} dt. \end{split}$$

Taking a diagonal subsequence, denote again as  $u^m$ , that satisfies (14) and (27) for a sequence of regular bounded open sets  $\mathcal{O}_j \subset \mathcal{O}$  that contain all supports of functions  $v_i$  of the basis. Passing to the limit, we have

$$\begin{split} &\int_{\tau}^{T} \left(\frac{du(t)}{dt}, u_{j}\psi(t)\right)_{g} dt + \nu \int_{\tau}^{T} \langle Au(t), v_{j}\psi(t) \rangle dt \\ &+ \nu \int_{\tau}^{T} (Cu(t), v_{j}\psi(t))_{g} dt + \int_{\tau}^{T} b(u(t), u(t), v_{j}\psi(t)) dt \\ &\int_{\tau}^{T} \langle f(t), v_{j}\psi(t) \rangle dt + \int_{\tau}^{T} (F(t, u_{t}), v_{j}\psi(t))_{g} dt \end{split}$$

holds for all  $v_j$  in the basis and any continuously differentiable function v on [0, T]. Thus, we see that u satisfies (3) in the distribution sense.

At the end of this section, we prove the following lemma, which has been used in the proof of Theorem 3.2.

Lemma 3.4. Under the assumptions of Theorem 3.2, the sequence  $u^m$  given in (4) is precompact in the following sense suppose a bounded open set  $\mathcal{O} \subset \Omega$  is given, then there exists a subsequence depending on  $\mathcal{O}$ , which we relabel, such that

$$u^{m}|_{\mathcal{O}} \rightarrow u|_{\mathcal{O}} in L^{2}(\tau, T, L^{2}(\mathcal{O}, g)),$$

where u is the limit given in (14).

To prove Lemma 3.4, we will use the following

Lemma 3.5. [11. Theorem 2.2] Let  $\Theta$  be a bounded open set of  $\mathbb{R}$  and  $X \subset E$  be Banach spaces with compact injection. Consider  $1 \leq r < q \leq \infty$ . Suppose  $F \subset L^{r}(\Theta, E)$  satisfies

(i)  $\forall \omega \subset \subset \Theta$ , sup  $\|\tau_h f - f\|_{L^r(\omega, E)} \to 0$  when  $h \to 0$ , where  $\tau_h f$  is the translation lation

$$(\tau_h f)(x) = f(x + h).$$

(ii) F is bounded in L<sup>q</sup>(Θ; E) ∩ L<sup>1</sup>(Θ; N)

Then F is precompact in  $L^{r}(\Theta; E)$ .

Proof of Lemma 3.4. Fix  $\chi \in C^1(\mathbb{R}_+)$  with  $\chi(s) = 1$  for  $s \in [0,1]$  and  $\chi(s) = 0$  for  $s \geq 4$ . Consider  $\mathcal{O}$  as in the statement, let R > 0 be such that  $\mathcal{O} \in B(0, R)$  and denote  $\mathcal{O}' = \Omega \cap B(0, 2R)$ , and  $u^{m,R}(x) = u^m(x)\chi[|x|^2/R^2)$ . Again the compactness holds for  $N = H_0^1(\mathcal{O}', g) \subset E = L^2(\mathcal{O}', g)$  with compact injection, and we conserve the original  $u^m$  on  $\Omega \cap B(0, R)$ .

For the sake of clarity, we continue the proof directly with  $u^m$  instead of  $u^{m,R}$ . Since condition (ii) in Lemma 3.5 is obviously satisfied by (10) and (11), we concentrate on (i). Actually, we will prove that for the whole domain  $\Omega$  the following property holds:

$$\sup_{m\in\mathbb{N}}\|\tau_h u^m-u^m\|_{L^2(0,T-h,L^2(\Omega,g))}\to 0 \text{ when } h\to 0$$

Consider h > 0 arbitrarily small. From (4) we deduce for  $(t, t + h) \subset (\tau, T)$  that

$$\begin{split} &\int_{\Omega}(u^{m}(t+h)-u(t))w_{j}gdx+\nu\int_{t}^{t+h}\int_{\Omega}\nabla u^{m}(s)\cdot\nabla w_{j}gdxds\\ &+\nu\int_{t}^{t+h}b(\frac{\nabla g}{g},u^{m}(s),w_{j})ds+\int_{t}^{t+h}b(u^{m}(s),u^{m}(s),w_{j})ds\\ &=\int_{t}^{t+h}\int_{\Omega}f(s)w_{j}gdxds+\int_{t}^{t+h}F(s,u_{s}^{m})w_{j}gdxds. \end{split}$$

Multiplying by  $\gamma_{m_j}(t + h) - \gamma_{m_j}(t)$  and summing in j we obtain

$$\begin{split} &\int_{\Omega} |u^{m}(t+h) - u(t)|^{2}gdx = -\nu \int_{t}^{t+h} \int_{\Omega} \nabla u^{m}(s)(\nabla u^{m}(t+h) - \nabla u^{m}(t))gdxds \\ &-\nu \int_{t}^{t+h} b \Big( \frac{\nabla g}{g}, u^{m}(s), u^{m}(t+h) - u^{m}(t) \Big) ds - \int_{t}^{t+h} b (u^{m}(s), u^{m}(s), u^{m}(t+h) - u^{m}(t)) ds \\ &+ \int_{t}^{t+h} \int_{\Omega} f(s) \cdot (u^{m}(t+h) - u^{m}(t))gdxds + \int_{t}^{t+h} \int_{\Omega} F(s, u_{s}^{m}) \cdot (u^{m}(t+h) - u^{m}(t))gds. \end{split}$$

The right-hand side may be bounded by

$$\begin{split} \nu |\nabla u^m(t+h) - \nabla u^m(t)| \int_t^{t+h} |\nabla u^m(s)| ds \\ + \nu \int_t^{t+h} \frac{|\nabla g|_{\infty}}{m_0 \lambda_1^{1/2}} \|u^m(s)\| |u^m(t+h) - u^m(t)| ds \end{split}$$

$$\begin{split} &+ \int_{t}^{t+h} c |n^{m}(s)| \|u^{m}(s)\| \|n^{m}(t+h) - u^{m}(t)\| ds \\ &+ \int_{t}^{t+h} \|f(s)\|_{*} \|u^{m}(t+h) - u^{m}(t)\| ds + \int_{t}^{t+h} |F(s,u_{s}^{m})| |u^{m}(t+h) - u^{m}(t)| ds. \end{split}$$

Thus, using (H2) and (10), we have proved that

$$\int_{\Omega} |u^{m}(t+h) - u^{m}(t)|^{2} g dx \leq ||u^{m}(t+h) - u^{m}(t)|| \int_{t}^{t+h} G_{m}(s) ds,$$

where the function  $G_m : \mathbb{R} \to \mathbb{R}$  is defined as:

$$G_{m}(s) = \nu \|u^{m}(s)\| + \nu \frac{|\nabla y|_{\infty}}{m_{0}\lambda_{1}} \|u^{m}(s)\| + cK_{1}\|u^{m}(s)\| + \|f(s)\| + \lambda_{1}^{-1/2} |F(s, u^{m}(s))|.$$

with  $K_1$  being a constant independent of m such that  $|u^m(s)| \leq K_1$ .

To finish the proof, we will estimate

$$\begin{aligned} \|\tau_h u^m - u^m\|_{L^2(\tau, T-h, L^2(\Omega, g))}^2 &= \int_{\tau}^{T-h} \int_{\Omega} |\tau_h u^m - u^m|^2 g dx dt \\ &\leq \int_{\tau}^{T-h} \|u^m(t+h) - u^m(t)\| \int_{t}^{t+h} G_m(s) ds dt. \end{aligned}$$

For the right-hand side, the Fubini theorem yields, using the function

$$\overline{s} = \begin{cases} 0 & \text{if } s \le 0, \\ s & \text{if } 0 < s \le T - h, \\ T - h & \text{if } s > T - h, \end{cases}$$

to

$$\begin{split} &\int_{\tau}^{T-h} \|u^{m}(t+h) - u^{m}(t)\| \int_{t}^{t+h} G_{in}(s) ds dt \\ &\leq \int_{\tau}^{T} G_{m}(s) \int_{s-h}^{\bar{s}} \|u^{m}(t+h) - u^{m}(t)\| |dt ds \leq 2(hK_{2})^{1/2} \int_{\tau}^{T} G_{m}(s) ds. \end{split}$$

where  $K_2$  is a constant independent of m such that  $\int_r^T \|u^m(s)\|^2 ds \leq K_2$ , and we have used the Young inequality and the facts that

$$0 \le \overline{s} - \overline{s-h} \le h$$
 for  $\int_{\overline{s-h}}^{\overline{s}} \|u^m(t+h) - u^m(t)\| dt$ ,

and

$$\int_{s-h}^{\overline{s}} \|u^{m}(t+h) - u^{m}(t)\| dt \leq \left(\int_{s-h}^{\overline{s}} dt\right)^{1/2} \left(\int_{s-h}^{\overline{s}} \|u^{m}(t+h) - u^{m}(t)\| dt\right)^{1/2}$$

$$\leq 2h^{1/2} \Big( \int_{r}^{T-h} \int_{\Omega} |\nabla u^{m}|^{2} g dr dt \Big)^{1/2} \leq 2h^{1/2} K_{2}^{1/2}.$$

To conclude, we observe that  $\int_{r}^{T} G_{m}(s) ds$  is bounded. Indeed, one has

$$\begin{split} \int_{\tau}^{T} &G_{m}(s) ds = \int_{\tau}^{T} \left[ \left( \nu + \nu \frac{|\nabla g|_{\lambda}}{m_{0}\lambda_{1}} + cK_{1} \right) \| u^{m}(s) \| + \| f(s) \|_{*} + \lambda_{1}^{-1/2} |F(s, u_{s}^{m})| ds \right] \\ &\leq \left( \nu + \nu \frac{|\nabla g|_{\infty}}{m_{0}\lambda_{1}} + cK_{1} \right) \sqrt{T - \tau} \left( \int_{\tau}^{T} \| u^{m}(s) \|^{2} ds \right)^{1/2} \\ &+ \sqrt{T - \tau} \left( \int_{\tau}^{T} \| f(s) \|_{*}^{2} ds \right)^{1/2} + \sqrt{T - \tau} \lambda_{1}^{-1/2} \left( \int_{\tau}^{T} |F(s, u_{s}^{m})| ds \right)^{1/2} \end{split}$$

and assumptions (H3)-(H4) give the bound for the two last terms.

### 4. Existence and stability of stationary solutions

In this section, we will study the existence and stability of a stationary solution to problem (1) under some additional conditions.

The restrictions we must impose to give sense to a stationary solution are that  $f \in V'_g$  and F are now autonomous, i.e. without dependence on time, and we must clarify how F acts over a fixed element of  $H_g$ . This is done with a slight abuse of potation in the following sense: We consider F(w) as F(w'), where  $w' \in C_{\gamma}(H_g)$  is the element that has the only value w for time  $t \le 0$ . Of course, as an immediate consequence of the assumptions for F, it follows that

$$|F(x_1) - F(x_2)| \le L_F |x_1 - x_2| \quad \forall x_1, x_2 \in H_q.$$

So, consider the following equation

$$\frac{du}{dt} + \nu Au + \nu Cu + B(u, u) = f + F(u_t) \quad \forall t \in (\tau, T).$$
(28)

A stationary solution to problem (28) is an element  $u^* \in V_g$  such that

$$\nu((u^*, v))_g + \nu(Cu^*, v)_g + b(u^*, u^*, v) = \langle f, v \rangle + (F(u^*), v)_g \quad \forall v \in V_g.$$
 (29)

Theorem 4.1. Under the above assumptions and notations, if

$$\nu(1 - \frac{|\nabla g|_{\infty}}{m_0 \lambda_1^{1/2}}) > \frac{L_F}{\lambda_1}$$

then

(a) Problem (28) admits at least one stationary solution u<sup>\*</sup>. Moreover, any such stationary solution satisfies the estimate

C. T. Anh, D. T. Quyet

$$\left[\nu(1 - \frac{|\nabla g|_{\infty}}{m_{0}\lambda_{1}^{1/2}}) - \frac{L_{F}}{\lambda_{1}}\right] ||u^{*}|| \le ||f||.$$
(30)

(b) If the following condition holds

$$\left[\nu(1 - \frac{|\nabla g|_{\infty}}{m_0 \lambda_1^{1/2}}) - \frac{L_F}{\lambda_1}\right]^2 > \frac{c_1}{\lambda_1^{1/2}} \|f\|_{*}.$$
(31)

where  $e_1$  is the constant in Lemma 2.1, then the stationary solution of (28) is unique.

*Proof.* (i) *Existence*. The estimate (30) can be obtained taking into account that in particular any stationary solution  $u^*$ , if it exists, should verify

$$\nu(Au', u') + \nu(Cu', u')_q = (f, u') + (F(u'), u')_q$$

and therefore

$$\nu ||u^*||^2 \le ||f||_* ||u^*|| + \frac{L_F}{\lambda_1} ||u^*||^2 + \frac{\nu |\nabla g|_{\infty}}{m_0 \lambda_1^{1/2}} ||u^*||^2.$$

For the existence, since  $V_g$  is separable there exists a sequence of linearly independent elements  $v_1, v_2, ...$  which is total in  $V_g$ . For each  $m \ge 1$ , let us denote  $V_m = \operatorname{span}\{v_1, ..., v_m\}$  and we would like to define an approximate solution  $u^m$ of (28) by

$$u^{m} = \sum_{i=1}^{m} \gamma_{mi} v_{i},$$
  

$$\nu((u^{m}, v_{i})) + \nu b(\frac{\nabla g}{g}, u^{m}, v_{i}) + b(u^{m}, u^{m}, v_{i}) = \langle f, v_{i} \rangle + (F(u^{m}), v_{i})_{g}, i = 1, \dots, m.$$
(20)

To prove the existence of  $u^m$ , we define operators  $R_m: V_m \rightarrow V_m$  by

$$(\langle R_m u, v \rangle) = \nu \langle Au, v \rangle + \nu \langle Cu, v \rangle_{\eta} + b \langle u, u, v \rangle - \langle f, v \rangle - \langle F(u), v \rangle_g \ \forall u, v \in V_m.$$

For all  $u \in V_{n_i}$ ,

$$\begin{split} ((R_m u, u)) &= \nu \langle Au, u \rangle + \nu (Cu, u)_g - \langle f, u \rangle - (F(u), u)_g \\ &\geq \nu \| u \|^2 - \| f \|_* \| u \| - \frac{LF}{\lambda_1} \| u \|^2 - \frac{\nu |\nabla g|_{\infty}}{m_0 \lambda_1^{1/2}} \| u \|^2 \\ &= \left( \nu (1 - \frac{|\nabla g|_{\infty}}{m_0 \lambda_1^{1/2}}) - \frac{LF}{\lambda_1} \right) \| u \|^2 - \| f \|_* \| u \|. \end{split}$$

Thus, if we take

$$\beta = \frac{\|f\|_{\bullet}}{\nu(1 - \frac{|\nabla g|_{\infty}}{m_0 \lambda_1^{1/2}}) - \frac{L_F}{\lambda_1}},$$

we obtain  $((R_m u, u)) \ge 0$  for all  $u \in V_m$  such that  $||u|| = \beta$ . Consequently, by a corollary of the Brouwer fixed point theorem (see [15, Chapter 2, Lemma 1 4]), for each  $m \ge 1$  there exists  $u_m \in V_m$  such that  $R_m(u_m) = 0$ , with  $||u_m|| \le \beta$ . Replacing  $v_r$  by  $u^m$  in (32) and taking into account that  $b(u^m, u^m, u^m) = 0$ , we get

$$\begin{split} \nu \|u^{m}(t)\|^{2} &= \langle f, u^{m} \rangle + (F(u^{m}), v^{m})_{g} - \nu b(\frac{\nabla g}{g}, u^{m}, u^{m}) \\ &\leq \|f\|_{*} \|v^{m}\| + \frac{L_{F}}{\lambda_{1}} \|u^{m}\|^{2} + \nu \frac{|\nabla g|_{\infty}}{m_{0}\lambda_{1}^{1/2}} \|u^{m}\|^{2}. \end{split}$$

Hence

$$\left[\nu(1 - \frac{|\nabla g|_{\infty}}{m_0 \lambda_1^{1/2}}) - \frac{L_F}{\lambda_1}\right] ||u^m|| \le ||f||_*.$$
 (33)

We extract from  $\{u^m\}$  a sequence  $\{u^m'\}$ , which converges weakly in  $V_g$  to some limit u. If  $\Omega$  is bounded, then the injection of  $V_g$  into  $H_g$  is compact. Thus, this convergence holds also in the norm of  $H_q$ 

 $u^{m'} \rightarrow u$  weakly in  $V_q$  and strongly in  $H_q$ ,

up to a subsequence. Passing to the limit in (32) with the sequence m', we find that u is a weak solution of (28). In the case that  $\Omega$  is unbounded, the injection of  $V_g$  into  $H_g$  is no longer compact. However, this difficulty can be overcome by using arguments as in [15, p. 168-171].

(ii) Uniqueness. Suppose that  $u^*$  and  $v^*$  are two stationary solutions of (28). Then

$$\nu(Au^{*}-Av^{*},v)+b(u^{*},u^{*},v)-b(v^{*},v^{*},v)+\nu(Cu^{*}-Cv^{*},v)_{g}=(F(u^{*})-F(v^{*}),v)_{g}$$

for all  $v \in V_q$ . Taking  $v = u^* - v^*$ , we have

$$\nu \langle Au^* - Av^*, u^* - v^* \rangle = b(v, v^*, v) - \nu (Cu^* - Cv^*, u^* - v^*)_g + (F(u^*) - F(v^*), u^* - v^*)_g$$

Hence

$$\nu \|u^* - v^*\|^2 \le c_1 \lambda_1^{-1/2} \|u^* - v^*\|^2 \|v^*\| + \frac{L_F}{\lambda_1} \|u^* - v^*\|^2 + \frac{\nu |\nabla g|_{\infty}}{m_0 \lambda_1^{1/2}} \|u^* - v^*\|^2$$

and therefore

$$\left[\nu(1 - \frac{|\nabla g|_{\infty}}{m_0\lambda_1^{1/2}}) - \frac{L_F}{\lambda_1}\right] \|u^* - v^*\|^2 \le c_1\lambda_1^{-1/2} \|u^* - v^*\|^2 \|v^*\|.$$
(34)

From (30) and (34) we have

C. T. Anh, D. T. Quyet

$$\left[\nu(1-\frac{|\nabla g|_{\infty})}{m_0\lambda_1^{1/2}})-\frac{L_F}{\lambda_1}\right]^2||u^*-v^*||^2 \le c_1\lambda_1^{-1/2}||f||_*||u^*-v^*||^2, \quad (35)$$

and the uniqueness follows from (31) and (35).

**Theorem 4.2.** Assume that the assumptions in Theorem 3.2 with f and F independent of time and (31) hold. Then there exists a value  $\lambda \in \{0, 2\gamma\}$  such that for the solution u(t) of (1) with  $\tau = 0$  and  $\phi \in C_{\gamma}(H_g)$ , the following estimates hold for all  $t \ge 0$ 

$$|u(t) - u^*|^2 \le e^{-\lambda t} (|\phi(0) - u^*|^2 + \frac{L_F}{2\gamma - \lambda} ||\phi - u^*||_{\gamma}^2), \tag{36}$$

$$\|u_t - u^*\|_{\gamma} \le \max\left\{ e^{-2\gamma t} \|\phi - u^*\|_{\gamma}^2, e^{-\lambda t} \left( |\phi(0) - u^*|^2 + \frac{L_F}{2\gamma - \lambda} \|\phi - u^*\|_{\gamma}^2 \right) \right\},$$
(37)

where u' is the unique stationary solution of (28).

Proof. Denote  $w(t) = u(t) - u^*$ , one has

$$\begin{split} \frac{d}{dt}(w(t),v)_g + \nu((w(t),v))_g + \nu(Cu(t),v)_g - \nu(Cu^*,v)_g + b(u(t),u(t),v) \\ -b(u^*,u^*,v) = (F(u_t) - F(u^*),v)_g \quad \forall t > 0, v \in V_g. \end{split}$$

From the energy equality, (H4-iii). Lemmas 2.1 and 2.3, and introducing an exponential term  $e^{\lambda t}$  with a positive value  $\lambda$  to be fixed later on, we obtain

$$\begin{split} \frac{d}{dt}(e^{\lambda t}|w(t)|^2) &= e^{\lambda t} \left[ \lambda |w(t)|^2 - 2\nu ||w(t)||^2 + 2\nu (Cu^* - Cu(t), w(t))_g \\ &\quad + 2(b(u^*, u^*, w(t)) - b(u(t), u(t), w(t))) + 2(F(u_t) - F(u^*), w(t))_g \right] \\ &\leq e^{\lambda t} \left[ \lambda |w(t)|^2 - 2\nu ||w(t)||^2 + \frac{2\nu |\nabla g|_{\infty}}{m_0 \lambda_1^{1/2}} ||w(t)||^2 \\ &\quad + \frac{2c_1}{\lambda^{1/2}} ||w(t)||^2 ||u^*|| + 2L_F ||u_1||_{\gamma} ||w(t)| \right]. \end{split}$$

Hence, using the Cauchy inequality with  $\delta > 0$  to be fixed later on and (30), we bave

$$\begin{split} & \frac{d}{dt} (e^{\lambda_1} | w(t) |^2) \leq e^{\lambda_1} \frac{E_F}{\delta} \| w_t \|_{\gamma}^2 \\ & + e^{\lambda_1} \Big[ \lambda \lambda_1^{-1} - 2\nu + \frac{\delta L_F}{\lambda_1} + \frac{2c_1 \| f \|_{\ast}}{\lambda_1^{1/2} (\nu(1 - \frac{\| \nabla g \|_{\infty}}{m_0 \lambda_1^{1/2}}) - \frac{E_F}{\lambda_1})} + \frac{2\nu | \nabla g |_{\infty}}{m_0 \lambda_1^{1/2}} \Big] \| w(t) \|^2. \end{split}$$

Therefore, integrating from 0 to t, we have

$$e^{\lambda t}|w(t)|^2 \le |w(0)|^2 + \frac{L_F}{\delta} \int_0^1 e^{\lambda s} ||w_s||_{\gamma}^2 ds$$

76

+ 
$$\left[\lambda\lambda_{1}^{-1} - 2\nu + \frac{\delta L_{F}}{\lambda_{1}} + \frac{2c_{1}\|f\|_{*}}{\lambda_{1}^{1/2}\left(\nu(1 - \frac{\nu(\nabla g)_{\infty}}{m_{0}\lambda_{1}^{1/2}}) - \frac{L_{F}}{\lambda_{1}}\right)} + \frac{2\nu|\nabla g|_{\infty}}{m_{0}\lambda_{1}^{1/2}}\int_{0}^{t} e^{\lambda s}\|w(s)\|^{2}ds.$$
  
(38)

In order to control the term  $\int_0^t e^{\lambda s} ||w_s||_2^2 ds$ , we proceed as follows

$$\int_{0}^{t} e^{\lambda s} \sup_{\theta \leq 0} e^{2\gamma \theta} |w(s+\theta)|^{2} ds$$

$$\int_{0}^{t} e^{\lambda s} \max \{ \sup_{\theta \leq -s} e^{2\gamma \theta} |w(s+\theta)|^{2}, \sup_{\theta \in [-s,0]} e^{2\gamma \theta} |w(s+\theta)|^{2} \} ds$$

$$\int_{0}^{t} \max \{ e^{-(2\gamma-\lambda)s} \|\phi - u^{*}\|_{\gamma}^{2}, \sup_{\substack{\theta \in [-s,0]}} e^{(2\gamma-\lambda)\theta} e^{\lambda(s+\theta)} |w(s+\theta)|^{2} \} ds.$$

So, if  $\lambda < 2\gamma$ . using the above equality in (38), we obtain

$$\begin{split} e^{\lambda t} |w(t)|^2 &\leq |w(0)|^2 + \frac{L_F}{\delta} ||\phi - u^*||_{\gamma}^2 \int_0^t e^{(\lambda - 2\gamma)s} ds + \left[\lambda \lambda_1^{-1} - 2\nu + \frac{\delta L_F}{\lambda_1}\right] \\ &+ \frac{2c_1||f||}{\lambda_1^{1/2} \left(\nu(1 - \frac{|\nabla g|_\infty}{m_0 \lambda_1^{1/2}}) - \frac{L_F}{\lambda_1}\right)} + \frac{2\nu |\nabla g|_\infty}{m_0 \lambda_1^{1/2}} + \frac{L_F}{\lambda_1} \int_0^t \max_{r \in [0,s]} e^{\lambda r} ||w(r)||^2 ds. \end{split}$$

Observe that the choice of  $\delta = 1$  makes that  $\delta \lambda_1^{-1} L_F + L_F (\lambda_1 \delta)^{-1}$  is minimal and the coefficient of the last integral becomes

$$\lambda \lambda_{1}^{-1} - 2\nu + \frac{2L_{F}}{\lambda_{I}} + \frac{2c_{I} \|f\|_{\star}}{\lambda_{1}^{1/2} \left[\nu(1 - \frac{|\nabla g|_{\infty}}{m_{0} \lambda_{1}^{1/2}}) - \frac{L_{F}}{\lambda_{1}}\right]} + \frac{2\nu |\nabla g|_{\infty}}{m_{0} \lambda_{1}^{1/2}}.$$
 (39)

Using (31), we have

$$-2\nu + \frac{2L_F}{\lambda_1} + \frac{2c_1 \|f\|_{\bullet}}{\lambda_1^{1/2} \left[\nu(1 - \frac{\|\nabla g\|_{\infty}}{m_0 \lambda_1^{1/2}}) - \frac{L_F}{\lambda_1}\right]} + \frac{2\nu |\nabla g|_{\infty}}{m_0 \lambda_1^{1/2}} < 0.$$

Thus, we can choose  $\lambda \in (0,2\gamma)$  such that (39) is negative. So, we can deduce that

$$e^{\lambda t}|w(t)|^2 \leq |w(0)|^2 + \frac{L_F}{2\gamma - \lambda}(1 - e^{(\lambda - 2\gamma)t})||\phi - u^*||_{\gamma}^2,$$

whence (36) follows.

Finally, (37) can be deduced as follows

$$\begin{split} \|w_t\|_{\gamma}^2 &= \sup_{\theta \leq 0} e^{2\gamma\theta} |w(t+\theta)|^2 \\ &= \max \Big\{ \sup_{\theta \in (-\infty, -t)} e^{2\gamma\theta} |w(t+\theta)|^2, \sup_{\theta \in [-t,0]} e^{2\gamma\theta} |w(t+\theta)|^2 \Big\} \end{split}$$

$$= \max \left\{ e^{-2\gamma t} \|\phi - u^*\|_{\gamma, \theta \in [-t, 0]}^2 \sup e^{2\gamma \theta} |w(t + \theta)|^2 \right\}$$

and the second term can be estimated using (36) and the fact that  $e^{(2\gamma - \lambda)\theta} \leq 1$  when  $\theta \leq 0$ .

Acknowledgements. This work was supported by Vietnam's National Foundation for Science and Technology Development (NAFOSTED). Project 101.01-2010.05.

#### References

- 1 C. T. Auh and D. T. Quyet, Long-time behavior for 2D non-autonomous g-Navier-Stokes equations. Ann. Pol. Math. 103 (2012), 277-302.
- H. Bae and J. Roh, Existence of solutions of the g-Navier-Stokes equations, Tanuanese J. Math. 8 (2004), 85-102.
- T. Caraballo and J. Real, Navier-Stokes equations with delays, Proc. R. Soc. Lond., Ser. A 457 (2001), 2441-2454.
- T. Caraballo and J. Real, Asymptotic behaviour of Navier-Stokes equations with delays, Proc. R. Soc. Lond., Ser. A 459 (2003), 3181-3194.
- T. Caraballo, A. M. Márquez-Durán and J. Real, Asymptotic behaviour of the three-dimensional o-Navier-Stokes model with delays, J. Math. Anal. Appl. 340 (2008), 410-423.
- M. J. Garrido-Atienza and P. Marín-Rubio, Navier-Stokes equations with delays on unbounded domains, Nonlinear Anal., T. M. A. 64 (2006), 1100-1118.
- Y. Hino, S. Murakami, T. Naito, Functional Differential Equations with Infinite Delay, Lecture Notes in Mathematics, Vol. 1473, Springer, Berlin, 1991.
- J Jiang and Y. Hou, The global attractor of g-N-wier-Stokes equations with linear dampness on R<sup>2</sup>. Appl. Math. Comput. 215 (2009), 1068-1076.
- M. Kwak, H. Kwean and J. Roh, The dimension of attractor of the 2D g-Navier-Stokes equations, J. Math. Anal. Appl. 315 (2006), 436-461.
- H. Kwean and J. Roh, The global attractor of the 2D g-Navier-Stokes equations on some unbounded domains, Commun. Korean Math. Soc. 20 (2005), 731-749.
- P. Minin-Rubio, J. Real and J. Valero. Pullback attractors for a two-dimensional Navier-Stokes model in an infinite delay case, *Nonlinear Anal.*, T. M. A. 74 (2011), 2012-2030.
- P. Marin-Rubio, A. M. Marquez-Durán and J. Real, Three dimensional system of globally modified Navier-Stokes equations with infinite delays, *Discrete Contin.* Dyn. Syst. Ser. B 14 (2010), 655-673.
- J. L. Lions, Quelques Méthodes de Résolution des Problèmes aux Limites non Linéaires, Dunod, Gauthier-Villars, Paris, 1969.
- J. Roh, Dynamics of the g-Navier-Stokes equations, J. Differ. Equations 211 (2005), 452-484.
- R. Temam, Navier-Stokes Equations. Theory and Numerical Analysis, 2nd edition, North-Holland, Amsterdam, 1979.